

GM100M

USER'S MANUAL FIELD INSTALLATION GUIDE TECHNICAL INFORMATION



Document Number: GM100_20180301_01 Rev. Number : **4.2** Issue Date: 03/01/2018

GENERAL INFORMATION

WARRANTY

- Gentec warrants that the product manufactured by the company and delivered hereunder will be free of defects in material and workmanship for a period of twelve months from the date of receiving the product by the purchaser.
- The purchaser shall promptly report in writing any failure to conform to this warranty to the company within said period. The company will, at its options, repair the defective item or provide a replacement free of charge upon receiving the returned item, provided that it has not been mishandled in its storage, installation, maintenance, and operation after being received by the purchaser. The purchaser shall ship the defective product back to the company only after receiving a written authorization of the company.
- The equipment should not be repaired or altered without prior written or verbal approval of the company or its authorized distributors. Failure to comply will void all warranty on the product.
- The effects of corrosion, erosion and normal wear and tear are specifically excluded from this warranty.
- THE COMPANY MAKES NO OTHER, EXPRESSED OR IMPLIED, WARRANTY OR REPRESENTATION OF ANY KIND WHATSOEVER. ALL IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSEARE HEREBY DISCLAIMED.

SAFETY

General safety precautions:

- 1. Only trained personnel certified by Gentec shall be permitted to adjust or repair the equipment.
- 2. Read all instructions carefully before operating the equipment.
- 3. Do not connect the equipment to an electrical supply of incorrect voltage and/or frequency.
- 4. Switch off the main power supply before opening the case front panel to do wiring inside the equipment unless otherwise instructed.
- 5. Do not short any signal wires at both ends of the transmitting cable.
- 6. Do not use the equipment outside the specified ambient temperature and humidity ranges. Do not operate the equipment when it is considered defective. Otherwise, it may not reliably deliver its expected functions.
- 7. The equipment is not intended to be and must not be used in potentially explosive atmospheres. Do not install the equipment at or close to locations where there is any actual or foreseeable risk of hazardous levels of flammable gases or vapors.

Table of Contents

| 1. Introduction | 3 |
|--|----|
| 1.1 Electrical and Physical Specifications | 5 |
| 2. Function and Appearance | 6 |
| 2.1 Front Panel | 6 |
| 3. Function Description | 7 |
| 3.1 Input And Output Wiring | 7 |
| 3.1.1 Main Screen | 8 |
| 3.1.2 Event Page | 11 |
| 3.1.3 Trend Chart | 12 |
| 4. Functions of Buttons | 13 |
| 5. Setting | 13 |
| 5.1 Parameter Setting for Analog Input | 13 |
| 5.2 Parameter Setting for Digital Input | 15 |
| 5.3 Parameter Setting | 16 |
| 5.3.1 Panel Setup | 16 |
| 5.3.2 Password Setting | 17 |
| 5.3.3 Parameter Setting for Communication | 17 |
| 5.3.4 Parameter Setting for Relay Output | 18 |
| 5.3.5 Parameter Setting for Analog Input | 19 |
| 5.3.6 DAQ Raw Data | 19 |
| 6. Field Installation | 20 |
| 7. Firmware of Device | 22 |
| 8. Maintenance and Troubleshooting | 23 |
| 9. Q&A | 24 |

Appendix

| 1. | Port, Connector and Switch Locations for Back Board | 25 |
|----|---|----|
| 2. | Dimensions and Drawings | 29 |
| 3. | Chassis and Front Panel Installation | 30 |
| 4. | DISS and Connectors for Different Gases | 31 |
| 5. | Transducer Installation for Remote Connection | 31 |
| 6. | Power Supply and Grounding | 32 |
| 7. | Wiring of Transducer to Screw Terminal | 33 |
| 8. | Modbus | 34 |
| 8. | Registers Map | 37 |
| | | |

Features:

GM-100 Area Alarm actively displays your medical gas information on a highly visible 10" TFT LCD screen. It is capable of handling up to **8 gases**, 14 relay inputs, 7 relay outputs and 2 analog outputs in one alarm covering all needs of hospital alarm and monitoring needs.

- On-site customization without the use of a laptop, tablet, or mobile device. Settings such as brightness, pressure, hysteresis, silence time, communication parameters, and high and low alarm conditions can be adjusted.
- 10" Touch Screen Display with Password protected interface
- Can be used as an area alarm, master or combination alarm.
- Full networking capabilities out of the box including Modbus RTU/TCP, UDP protocols.
- Can be integrated with SCADA system or BMS systems
- Transducers can be mounted locally or remotely utilizing shielded twisted pair wiring up to 100 ft (30.5 m)
- Gas specific DISS fitting to ensure that the transducer is connected to its corresponding gas.
- Circuitry protection and detection, if the transducer is not connected at all or not to the appropriate gas display, an error message (No Sensors) will be displayed.
- The alarm system allows users to have optional relay outputs according to single or multiple alarm conditions.
- Event Log to view history of time stamped alarm events

1.1 Electrical and Physical Specifications

| MECHANICAL | |
|--------------------------|--|
| Front Panel | ABS |
| Case Body | Metal Alloy |
| Nominal Physical | Overall Size: 193mm x 280mm x 103mm (Height x Width x Depth) |
| Dimensions | Beneath the Wall:181mm x 262mm x 98 mm (Height x Width x Depth) |
| Wall Mounting Opening | 181mm x 262mm (Height x Width) |
| ENVIRONMENT | |
| Ambient Temperature | 0°C ~ 50°C |
| Ambient Humidity | 10% ~85% RH, non-condensing |
| Cooling | Natural Air Cooling |
| ELECTRICAL | |
| Power Requirements | Input : 100~240 VAC, 50~60Hz, 115V, 1.5A/230V, 1A |
| Processor | 32-bit RISC Microcontroller |
| | LCD Size : 10.1" TFT, LED Backlit |
| | Resolution : 1024x600 Pixels |
| Monitor | Color Depth : 16 bit, 65536Colors |
| | Brightness: 200 cd/m2 |
| | Louch Screen : 4-wire resistive (Hardness 4H) |
| | Durability : 50000 nours |
| Buttons | Resistive touch buttons |
| Buzzer | Adjustable Volume (95dB Max.) |
| COMMUNICATION | |
| RS-485Modbus RTU | 9600/19200 baud rate, (8,N,1) |
| UDP | Modbus RTU over UDP |
| Modbus TCP | 10/100M Automatic Selection |
| INPUT AND OUTPUT | |
| | Number of Channels : 8 |
| Analog Input | Input : 4-to-20 mA Double-wire Transmitter Input |
| | ADC Resolution : 14 bit or Range of Sensor within ±1% |
| Divital lawy | Number of Channels : 14 |
| Digital Input | Input : Dry Contact or TTL |
| | Number of Channels:7 |
| Relay Output | Maximum load:1A at 30VDC/0.5A at 120VAC |
| | Number of Channels : 2 |
| Analog Output | Maximum load:0-20mA(maximum), in relation to 1~5V current for4~20 mA |
| | Double-wire Transmitter |

2.FUNCTION AND APPEARANCE

2.1 FRONT PANEL

1. Main Screen 2. Touch Buttons

2.2 FUNCTION OF FRONT PANEL

Main screen is divided into two sections: upper section is for display and lower section is for touch buttons.

- (1) Homepage: Shows pressure value, gauge indicator, gas type and high or low alarm conditions.
- (2) Event log: keeps a time stamped record and cause of all alarm activity.
- (3) Trend chart: Shows the trend line of pressure value.

(4) Parameter Setting: Upon entering password, user can set up analog and digital alarm condition, analog and relay output condition as well as other setups.

(5) Test: press the button to test if buzzer works. If it does, the siren will sound twice.

(6) Silence: Shows condition of buzzer (Mute/Unmute). Press the button to silence the buzzer when siren arises.

3.FUNCTION DESPCRIPTIOON

3.1 INPUT AND OUTPUT WIRING

Pressure Monitoring: when GM100M is used as area alarm, it can monitor up to eight gases which occupy different input channel as follows:

| Analog Input Channel | Gas Type | Wiring |
|----------------------|----------------|------------------|
| S1 | OXYGEN | |
| S5 | CARBON DIOXIDE | |
| S2 | VACUUM | |
| S6 | NITROUS OXIDE | 80A & 83A serial |
| S3 | MEDICAL AIR | die . |
| S7 | WAGD/AGSS | |
| S4 | NITROGEN | Sx 2 |
| S8 | INSTRUMENTAIR | P51 & P52 serial |

Relay Output: Seven sets of relay output are assigned as follows:

Users can set custom outputs based on alarm condition(s), including analog input too low, analog input too high, digital input alarm and buzzer alarm output.

Default setup is as follows:

| RELAY NO. | FUNCTION |
|-----------|----------------------|
| 1 | OXYGEN ALARM |
| 2 | VACUUM ALARM |
| 3 | MED. AIR ALARM |
| 4 | NITROGEN ALARM |
| 5 | CARBON DIOXIDE ALARM |
| 6 | NITROUS ALARM |
| 7 | Buzzer Triggered |

Digital Input: Provides up to 14-digital inputs for dry contact or TTL for master alarm.

Analog Output: Provides up to 2 output channels for 4~20mA. Users can select and duplicate any output channel

3.1.1 MAIN SCREEN

Display of homepage depends on the purpose and the number of gas monitored. GM100M provides area, master or combination alarm signals as required by the latest edition of NFPA99. Display pages for common gas monitored are as follows:

Combo alarm

Master alarm

50

45

HH

55

60

All monitoring display is divided into two categories, namely, analog input display and digital input display components. The display is as follows:

Elements of analog input module are explained as below:

Default display of gauge indicator when number of monitored gas is above five.

OXYGEN

DS

35.0

- (1) **Channel Identification Label**: Displays the type of gas or label of measuring condition by text and color coding. Press the label to set up after entering password.
- (2) Low Alarm Indicator

monitored gas is under four.

- Gray: Data is within the normal range
- Blink red: Data has reached the low alarm limit.
- (3) **Digital Gauge Scale:** Provides easy visual identification of alarm condition and trend based on where the needle is pointing on the color coded scale. (Green area: condition is normal, Red Area: alarm condition triggered)

(4) Channel Identification

(5) Numerical Data Display:

a. Data is in high or low limit range: When the value has reached the set high or low limit, the numerical value becomes a red font and blinks as a visual alarm indicator.b. Data is within normal range: When data is within the normal range, the numerical value is displayed as a green font.

c. Silenced Alarm Condition: When a user silences the audio alarm, the display will show a red background with numerical value shown in a black font.

d. Data is close to high or low limits: Numerical value will be displayed in a yellow

font.

- (6) High Alarm Indicator
 - Gray: Data is within the normal range
 - Blink Red: Data has reached the high alarm limit.
- (7) Unit of Measure: for display of Unit of Measurement

Elements of digital input module are explained as blow

- Digital Input Light
 Gray: No alarm.
 Red: Alarm triggered.
 Yellow: Caution, alarm limit almost reached but alarm not triggered
- (2) **Channel Identification Label**: Displays the type of gas or label of measuring condition by letters and color. Press the label to set up after entering password.

3.1.2 EVENT LOGS

Press "Event Log" button to enter event history. The page maintains a rolling list of the 200 most recent alarm events. The date, duration, and time of the event will be logged as well as the alarm trigger condition. Press up and down buttons to flip pages to check other events.

3.1.3 Pressure Trends

Press the "Pressure Trends" button to enter page showing trends of pressure value from analog input. The page maintains 24 hours of the most recent pressure trends. Roll the bar on the bottom to check other trending of pressure values.

4. FUNCTION OF BUTTONS

| Main Alar Tabl | m e Trend () Setup Test 2017/03/10 11:22:32 | | |
|-------------------|---|--|--|
| Main | Homepage Press the button to go back to the main page. | | |
| Alarm Table | Event Log Press the button to switch to the event log page. | | |
| Trend | Pressure Trends Press the button to switch to the pressure trends page. | | |
| Setup | Setup A password prompt will display after pushing the "setup" button. Enter the correct password to access the system settings. Press the "setting" button again to go back to setting page. | | |
| Test | Test Press the button to test if buzzer works. The siren shall beep twice. | | |
| | Silence When buzzer is activated, the color of image will turn red and siren will arise. Press the button to silence buzzer (the default setting is to silence the alarm for 60 seconds). | | |

Functions of buttons are described below:

In the following sections, we will describe the contents and operation of each setting page.

5. SETUP

Pressing the Channel Identification Label or "Setup" button brings up a password prompt. Enter the correct password to access the system settings.

Enter the password to enter the settings menu (the default password is 111111). After entering the correct password, the window will disappear and jump to the setup page.

5.1.PARAMETER SETTING FOR ANALOG INPUT CHANNEL

| Analog Input Setup | |
|---|----------------------------|
| | Unit |
| Channel 1 Enable | psi 💌 |
| Sensor To (mV) : 1000 To (mV) : 5000 5000 5000 10000 10000 10000 </th <th></th> | |
| P. V. From: 0.000 P. V. To: 100.000 | |
| Limit Lower: 40.000 Upper: 60.000 | |
| Others Hsyteresis(P. V.): 0.000 | Save |
| SilenceTime(min): -1 | Dave |
| P.U> Physical Value | |
| | |
| Main Table Trend Setup I | est 2017/02/10 15:04:55 |

Pressing an item brings up a password prompt. Enter the correct password to access the analog input parameter settings. Press on the fields to modify and an onscreen keyboard will allow access to modify values. Press "SAVE" to save changes made. The modifiable parameters are as follows:

(1). Input Signal Range.

"From (mV)" Sands for the minimum output voltage from the transmitter (in mV). " To (mV)" : Stands for the maximum output voltage from the transmitter (in mV). (The analog input load resistance of this system is 250Ω , so 4 to 20mA input is equivalent to 1000 to 5000 mV).

- (2). "P.V. From" (Physical Value From): The physical value of the transducer's read-in data for output voltage at its lowest value.
 "P.V. To" (Physical Value To): The physical value of the transducer's read-in date for output voltage at its highest value.
 For example, the read-in data of voltage should be 0 psig when it is a two-wire transducer outputting 4mA; and the read-in data of voltage should be 100 psig when it is two-wire transducer outputting 20mA for a pressure transducer range of 0-100 psig 4-20 mA.
- (3). Lower (Lower Limit). Upper (Upper Limit). (E.g. : 40 psig and 60 psig). "Limit" these values will define the lower and upper limits for alarm conditions.

Lower: alarm value to lower limit.

Upper: alarm value for upper limit

(For example: 40 psig lower limit and 60 psig higher limit, alarm will trigger when pressure reaches 40 psi on the lower limit and also trigger when pressure reaches the 60 psi upper limit.

- (4). Silence time: The unit of measure is by minute(s). User can silence the buzzer for a few minutes by pressing "Silence" icon button when alarm is triggered. The silence time duration can be altered here by entering a value above "0". To disable the mute function (buzzer cannot be turned off) change the value to "0". To infinitely mute the buzzer, change the value to "-1".
- (5). Hysteresis: Is a buffer function to ensure monitored values have returned to the functional state after an alarm condition arises and the problem is solved before alarm conditions return to normal state. For example, if the alarm upper limit is set to 60 and the hysteresis value is 5, an alarm will be generated when the data reaches 60, and will not shut off until the value returns to 5 less than the alarm condition of 60. In this example, the alarm condition will remain until the monitored value returns to 55. Similarly, if the lower alarm limit is set to 35 and the alarm hysteresis is set to 5, the device will alarm when the sampled value is less than or equal to 35 and the alarm state will not deactivate immediately after the sampling value is greater than 35. The device will exit the alarm state when the value is greater than or equal to 40.
- (6). Pressure unit selection (psi, mmHg, inHg, kPa, MPa and bar): the change of unit of measure actives immediately.

5.2.PARAMETER SETTING FOR DIGITAL INPUT CHANNEL

| Digital Input 3 Setup | | | | | | | | | |
|-----------------------|---------------|----------------|--------------|-----------------|---------------|---------------|--------------|-----------------|----------------|
| | Input Type | High Alarm | Low Alarm | Silence Time | Input Type | High Alarm | Lou Alarm | Silence Time | |
| | | | | | | | | | Active |
| | | | | | | | | | Inactive |
| | Ch3 Relay | | Low Alarm | 60 | | | | | Saua |
| | | | | | | | | | Save |
| | | | | | | | | | |
| | | | | | | | | | |
| | | | | | | | | | |
| | Main | Alarm Table | Tre | end | 4)) | Setup | Те | st 2017/ | 03/10 10:35:25 |

Pressing an icon brings up a password prompt. Enter the correct password to access the digital input parameter settings. Press on the fields to modify and an onscreen keyboard will allow access to modify values. Enter values desired and click SAVE to save changes. The setup parameters are:

- (1). Dry contact or TTL digital inputs.
- (2). The buzzer will be enabled when the read-in data is High (Open).
- (3). The buzzer will be enabled when the read-in data is Low (Closed).
- (4). The unit of measure for silence time is by the minute.

To avoid false alarms, user should disable the channels not in use.

5.3. SYSTEM PARAMETER SETUP

Pressing an icon brings up a password prompt. Enter the correct password to access the system parameter settings. Press on the fields to modify and an onscreen keyboard will allow access to modify values. Enter values desired and click SAVE to save changes.

5.3.1. PANEL SETUP

Press on a field for the onscreen keyboard, enter numbers and click "SAVE" to save changes. The setup parameters are as follows:

- (1) Date and time.
- (2) Brightness: press up and down buttons to adjust brightness.
- (3) Screen Saver: Screen Saver will be activated based on set value. Deactivate the screen saver function by entering the value "0"
- (4) Keyboard Click Sounds: Press the icon to activate or deactivate click sounds.

5.3.2. PASSWORD SETTING

Press the box for the onscreen keyboard to enter a new 6 digit password and click SAVE.

5.3.3. PARAMATER SETTING FOR COMMUNICATION

Press an item for onscreen keyboard to enter numbers and click SAVE to save changes. The setup parameters are:

- (1). IP Address: the default setup is 192.168.0.18.
- (2). Mask: the default setup is 192.168.0.18. Mask decides traffic of network. Do not change setup unless it is necessary.
- (3). Gateway: the default setup is 192.168.0.1.
- (4). UDP Port: the default setup is 48000.
- (5). Modbus RTU ID (range from 1~247): Either adopting Modbus-TCP, UDP or RS232/485, Modbus ID has to be set up correctly to communicate with modules. Modbus RTU Baudrate (9600 or 19200) °

5.3.4. PARAMATER SETTING FOR RELAY OUTPUT

Press Previous and Next to select a relay output and press the selected item to set up. Click "SAVE" to save changes.

Parameters to set up are as follows:

- (1). Select remote or screen to control the relay output.
- (2). When read-in data of channels 1-8 for analog or read-in data of channels 1-14 for digital input causes an alert, channels 1-7 relays can be selected to short-circuit or open-circuit output. The relay short-circuit or open-circuit is selected by the Action button.

NOTE: If buzzer is selected as actuating action for relay output, other selection(s) should be disabled to prevent false alarm.

5.3.5. PARAMETER SETTING FOR ANALOGOUTPUT

| Analog | Output Setup | |
|------------------|---|---------------------|
| DAC1 = REMOTE | DAC2 = REMOTE REMOTE ADC CH1 ADC CH2 ADC CH3 ADC CH4 ADC CH5 ADC CH6 ADC CH7 ADC CH8 | Save |
| Main Alarm Trend | Setup Test | 2017/05/04 12:29:54 |

Select the analog output: 1) remotely (or from the screen) or 2) copy the channel number of the analog input as output.

5.3.6. DAQ RAW DATA DISPALY

The page displays read-in voltage data from ADC, raw data of digital input and relay output.

6. FIELD INSTALLATION

NOTICE: Normally, the display module will be dispatched along with the other components CAUTION: Field installation is not allowed without certified technician supervised.

The module assembly consists of three sections:

(1) Front Panel:

The data-access PCB and display panel are mounted onto the front panel.

(2) Metal Case

Power supply, fuse and power switch are mounted inside the metal case.

(3) Transducer:

Sensors with brass, DISS connectors for different gases. The actual brass, DISS connector, the number of sensors, the number of components vary according to the different systems.

Parts of transducer vary from gas type. The actual coupling tube, DISS connector and quantity of transducer vary from system to system.

STEP 1: Case Mounting

Prepare a wall opening of the dimensions (see Appendix 2). Make sure locations of wall-mounting screw holes match the ones of case body so it will fit in the wall opening. For the front panel to secure on to case body, make sure the shape of case body is not distorted out of being embedded in the wall opening.

STEP 2: Install Coupling Tube with DISS

Each DISS comes with a label of gas type (see Appendix 4). If transducer is installed inside the case, DISS on coupling tube should be welded onto corresponding gas pipe (see Appendix 3). Do not damage DISS while installation is undergoing.

STEP 3: Pressure Test

Medical Gas Pipeline system should be pressurized according to NFPA 99 standard to check all welding connections.

STEP 4: Transducer Installation

Transducer Inside the Case (Local)

Each DISS on coupling tube comes with a gas label, so does connector and transducer.

- 1. Make sure the DISS is connected to the corresponding transducer.
- 2. Secure the DISS onto transducer and make sure there is no gas leakage.
- 3. Check the pressure range of the transducers installed meet the specification of the intended gas:

Low pressure transducers: 0~100psi (oxygen, medical air, nitrous oxide and carbon dioxide). High pressure: 0~300psi (nitrogen, instrument air, hyperbaric oxygen). Negative pressure: 0~30inHg/760mmHg (vacuum, WAGD)

Transducer Outside the Case (Remote)

- 1. Secure a T-shape ¹/₄ " NPT female onto transducer (see Appendix 5).
- 2. Take down check valve on DISS and secure T-shape gas distribution connector onto it.
- Secure check valve onto transducer and make sure there is no gas leakage. Connect lead and wire of transducer to communication cable inside case. Specification of the communication cable should be 22AWG insulated and its length should not be longer than 30 meters.

STEP 5: Display Module Assembly Installation (see Appendix 3)

- 1. Secure hinges of display module assembly onto screw holes on the bottom of metal case
- 2. Secure retaining strings of display module assembly onto screw holes of on the sides of metal case.

NOTICE: Make sure no static electricity cause damage to the circuit board on display module during or prior to assembly.

STEP 6: Power Supply Installation (see Appendix 3 and 6)

NOTICE: Switch DC power supply to "OFF" position before installing display module assembly, wiring or replacing transducer.

- 1. Make sure the switch of power supply is at "OFF" position.
- 2. Connect the DC power of metal case to the DC power of display on module assembly.
- 3. Connect the AC power to the AC power supply Terminals on power supply board. AC power wires must run thru the conduit to the metal case of prepunch hole.
- 4. Connect the earth ground lead to the earth ground terminal. AC Supply 'GND' terminal is connected to the Building Earth directly. Make sure the earth ground terminal is connected to metal case with washer nut. After the 'GND' terminal is connected to the Building Earth, this terminal must be connected to the 'ground' of the power supply with a bonding conductor.

STEP 7: Screw Terminal Wiring (See Appendix 7)

Transducer Inside the Metal Case (take oxygen transducer for example):

- Connect the red lead of transducer to DIP switch V of screw terminal on display module assembly and the black lead of transducer to DIP switch ai1 of screw terminal on display module assembly. DIP switch can be taken down while users conduct wiring.
- 2. Repeat the step above to connect other leads of transducer to screw terminal.

Assignments of DIP Switch

| V & ai1 | V & ai5 | V & ai2 | V & ai6 | V & ai3 | V & ai7 | V & ai4 | V & ai8 |
|---------|------------------|---------|-------------------|-------------|------------|----------|-------------------|
| OXYGEN | CARBON DIOXDE | VACUUM | NITRIOUS OXIDE | MED. AIR | WAGD | NITROGEN | INSTRUMENT AIR |

Transducer Outside the Metal Case (take oxygen transducer for example):

- 1. Make sure the communication cable is 22AWG insulated and its length should not be longer than 30 meters.
- 2. Connect the positive lead of communication cable to DIP switch V of screw terminal on display module assembly and the negative one of communication cable to DIP switch ai1. The screw terminal on display module assembly can be taken down while users conduct wiring.
- 3. Repeat Step 1 above to connect other leads of transducer to DIP switches.

Analog Output Installation (4~20mA output channel 1)

- 1. Make sure the communication cable is 22AWG insulated and its length should not be longer than 30 meters.
- 2. Connect the positive lead of communication cable to DIP switch o1 of screw terminal on display module assembly.
- 3. Connect the negative lead of communication cable to DIP switch G of display module assembly. The screw terminal on display module assembly can be taken down while users conduct wiring.

Digital Input Installation (Input Channel 1)

- 1. Make sure the communication cable is 22AWG insulated.
- 2. Connect the positive lead of communication cable to DIP switch i1 of screw terminal on display module assembly.
- 3. Connect the negative lead of communication cable to DIP switch G of screw terminal on display module assembly. The screw terminal on display module assembly can be taken down while users conduct wiring.

Relay Output Installation (Relay Output Channel 1)

- 1. Make sure the communication cable is 22AWG insulated.
- 2. Connect the positive lead of communication cable to DIP switch +1 of screw terminal on display module assembly.
- 3. Connect the negative lead of communication cable to DIP switch -1 of display module assembly. The screw terminal on display module assembly can be taken down while users conduct wiring.

RS-485 cable Installation

- 1. Make sure the cable specification is 22AWG twisted pair and insulated.
- 2. Connect the positive lead of RS-485 cable to the positive pin of screw terminal.
- 3. The screw terminal on display module assembly can be taken down while users conduct wiring.
- 4. Connect the insulated lead of RS-485 cable to DIP switch S on screw terminal. The screw terminal on display module assembly can be taken down while users conduct wiring.
- If the alarm is the last device on the RS-485 network, the dip switch of the last module of the alarm must be turned off.

STEP 8: Swing the Display Module Assembly Upward (see Appendix 3)

- 1. Switch power supply to "ON" position and make sure the system works normally.
- 2. Swing the display module assembly upward and check the retaining string is inside the metal case.
- 3. Secure the display module assembly onto the metal case using the screw holes at the top edges of the metal case and the module assembly.

STEP 9: Parameters Setting

Please refer to Chapter 4.1 for parameters setting if any modification is needed.

7. Firmware of Device

Since GM100 uses microcontroller to control all signals, any change of firmware is not allowed by user. The version of firmware is attached on backboard.

8. MAINTEINANCE AND TROUBLESHOOTING

Environmental uncertainty may degrade efficiency of the alarm system; therefore, a routine maintenance check (about every six to twelve months) of your PLC and control system is good practice, and should include the following items:

| NO. | ITEM | CHECK | CONDITION | SOLUTION |
|---------------------|------------------------------|---|--|--|
| 1 | Power Supply | If AC voltage is exceeding nominal value | The specification for AC power supply should be between 100~240 VAC. | Use AC volt meter check if AC power supply is within the range |
| 2 | Voltage Input / Output | If input or output voltage is exceeding nominal value. | The specification for input or output voltage should be within nominal value. | Use AC volt meter check if AC power supply is within the range. |
| | | Temperature | 0 to 55°C | Use thermometer to measure temperature. |
| | | Humidity | 10%~90~ RH, non- condensing | Use hygrometer to measure humidity and adjust humidity to be within specifications if possible. |
| | | Direct Sunlight Exposure | Direct sunlight exposure is not allowed | Keep alarm away from sunlight exposure. |
| 3 | Environment | If there are any particles, salts or metallic shavings accumulations in exterior. | Any particles, salts or metallic shavings accumulation is not allowed. | Clean up exterior case if needed. |
| | | If there are any splash of liquid, oil, stain or chemical. | Splash of liquid, oil , stain or chemical is not allowed. | Clean up exterior case if needed |
| | | Check for telecomm interference. | Telecom interference is not allowed | Keep alarm away from telecom interference. |
| | | If there is any shaking movement? | Avoid shaking movement to alarm. | Use foam as shock absorber if necessary. |
| | | If wiring is correct and tightened. | Insufficient tightening is not allowed. | Reconnect the loose wire and make sure it is tightened. |
| 4 | Wiring | Inspect mechanics and screws for wiring. | Insufficient tightening is not allowed. | Make sure the loose screw is tightened. |
| | | Inspect wiring condition. | No cable damage is allowed. | Replace damaged cables for new ones. |
| 5 Buzzer Testing | | Press the button to test alarm. | If Buzzer does not sound | Send alarm back for maintenance. |
| 6 | Touch Screen Testing | Press buttons on screen | Alarm system will switch to its pages respectively when buttons are pressed. | Send alarm back for maintenance. |

1. How to make sure wiring for transducer is correct?

To get to DAQ Raw Data Display, press correct password then press item DAQ Raw Data Display. It will display read-in data of voltage and digital input. Users can tell if wiring of transmitter is correct from read-in voltage. For example, the system has to serve a load of 250mA, the read-in data of voltage should be 1000mV when it is two-wire transmitter outputting 4mA; and the read-in data of voltage should be 5000mV when it is two wire transmitter outputting 20mA. If read-in data of voltage is incorrect, please check if the wiring of transmitter is solid.

Contact your retailer

If you fail to operate the system, please contact your retailer or Gentec Systems Corporation.

APP. 1. PORT, CONNECTOR AND SWITCH LOCATIONS FOR BACK BOARD

- (1). DC Power Supply
- (2). RS-232 at TTL Level
- (3). Connector for Analog Input and Transducer(4). Dry Contact Output Interface
- Connector for Digital Input (5).
- (6).
- Connector for RS-485 Screw Terminal Connector for 4~20mA Analog Output (7).
- Connector for 10/100M, auto selection (8).
- (9). Reset Button
- (A). Dip Switch for Function Selection
- Connector for Firmware Download (B).
- (C). Dip Switch for Signal Input Type Selection
- (D). Buzzer
- Buzzer Volume Adjustment Knot (E).
- External Output for Buzzer (F).
- (G). Dip Switch for RS-485 Terminating Resistor

Functions of connectors described as below:

(1). DC Power Supply

| PIN NUMBER | V | G | S |
|------------|----------------|-----|-------------------|
| ASSIGNMENT | DC +12~24VV | GND | Chassis Ground |

(2). Connector for RS-232 at TTL Level: the connector is compatible with TFT LCD display connector

| PIN NUMBER | 1 | 2 | 3 |
|------------|-----|-----|-----|
| ASSIGNMENT | TXD | RXD | GND |

(3). Connector for Analog Input and Transducer

| INPUT AND OUTPUT CONNECTIONS | | | | |
|------------------------------|--|--|--|--|
| SCREW TERMINAL | MINAL ASSIGNMENT | | | |
| V | 2-to-20 mA Double-wire Transmitter DC Power Supply | | | |
| S1 | Channel 1 for Analog Input | | | |
| V | 2-to-20 mA Double-wire Transmitter DC Power Supply | | | |
| S5 | Channel 5 for Analog Input | | | |
| V | 2-to-20 mA Double-wire Transmitter DC Power Supply | | | |
| S2 | Channel 2 for Analog Input | | | |
| V | 2-to-20 mA Double-wire Transmitter DC Power Supply | | | |
| S6 | Channel 6 for Analog Input | | | |
| G | Analog Input Common (Ground) | | | |
| V | 2-to-20 mA Double-wire Transmitter DC Power Supply | | | |
| S3 | Channel 3 for Analog Input | | | |
| V | 2-to-20 mA Double-wire Transmitter DC Power Supply | | | |
| S 7 | Channel 7 for Analog Input | | | |
| V | 2-to-20 mA Double-wire Transmitter DC Power Supply | | | |
| S4 | Channel 4 for Analog Input | | | |
| V | 2-to-20 mA Double-wire Transmitter DC Power Supply | | | |
| S8 | Channel 8 for Analog Input | | | |
| G | Analog Input Common (Ground) | | | |

(4). Dry Contact Input Interface

| INPUT AND OUTPUT CONNECTIONS | | | | | | |
|------------------------------|-------------------------------|-----------------------|---|--|--|--|
| Relay No. | Terminals CONNECTION FUNCTION | | FUNCTION DESCRIPTION | | | |
| 1 | 1+ | Relay 1 Common | Action Close : Alert 1+,1- shortage No Alert 1+,1- open | | | |
| | 1- | Relay 1 Normally Open | Action Open: Alert 1+,1- open No Alert 1+,1- shortage | | | |
| 2 | 2+ | Relay 2 Common | Action Close : Alert 2+,2- shortage No Alert 2+,2- open | | | |
| | 2- | Relay 2 Normally Open | Action Open. Alert 2+,2- open No Alert 2+,2- shortage | | | |
| 3 | 3+ | Relay 3 Common | Action Close : Alert3+,3- shortage No Alert 3+,3- open | | | |
| | 3- | Relay 3 Normally Open | Alert 3+,3- open No Alert 3+,3- shortage | | | |
| | 4- | Relay 4 Common | Action Close : | | | |
| 4 | 4+ | Relay 4 Normally Open | No Alert 4+,4- shortage No Alert 4+,4- open Action Open: Alert 4+,4- open No Alert 4+,4- shortage | | | |
| | 5+ | Relay 5 Common | Action Close : | | | |
| 5 | 5- | Relay 5 Normally Open | Alert 5+,5- shortage No Alert 5+,5- open Action Open: Alert 5+,5- No Alert 5+,5- shortage | | | |
| 6 | 6+ | Relay 6 Common | Action Close : | | | |

| | | | Alert 6+,6- shortage |
|---|-------------------------|-------------------------|--------------------------|
| | | | No Alert 6+,6- open |
| | 6- | Relay 6 Normally Open | Action Open: |
| | | | Alert 6+,6- open |
| | | | No Alert 6+ ,6- shortage |
| | 7+ | Relay 7 Common | Action Close : |
| | • | | Alert 7+,7- shortage |
| 7 | 7- Relay 7 Normally Ope | | No Alert 7+,7- open |
| | | Relay 7 Normally Open | Action Open: |
| | | ridiay / ridiniany Open | Alert 7+,7- open |
| | | | No Alert 7+.7- shortage |

(5). 14 Channels of Digital Input Connector

| INPUT AND OUTPUT CONNECTIONS | | | |
|-----------------------------------|----------------------------------|--|--|
| SCREW TERMINAL | ASSIGNMENT | | |
| l1+ | Channel 1 - Non-inverting Input | | |
| l1- | Channel 1 - Ground | | |
| 12+ | Channel 2 - Non-inverting Input | | |
| 12- | Channel 2 - Ground | | |
| 13+ | Channel 3 - Non-inverting Input | | |
| 13- | Channel 3 - Ground | | |
| 14+ | Channel 4 - Non-inverting Input | | |
| 14- | Channel 4 - Ground | | |
| 15+ | Channel 5 - Non-inverting Input | | |
| 15- | Channel 5 - Ground | | |
| 16+ | Channel 6 - Non-inverting Input | | |
| I6- Channel 6 - Ground | | | |
| I7+ Channel 7 - Non-inverting Inp | | | |
| I7- Channel 7 - Ground | | | |
| I8+ Channel 8 - Non-inverting In | | | |
| 18- | Channel 8 - Ground | | |
| 19+ | Channel 9 - Non-inverting Input | | |
| 19- | Channel 9 - Ground | | |
| l10+ | Channel 10 - Non-inverting Input | | |
| l10- | Channel 10 - Ground | | |
| l11+ | Channel 11 - Non-inverting Input | | |
| l11- | Channel 11- Ground | | |
| l12+ | Channel 12 - Non-inverting Input | | |
| l12- | Channel 12 - Ground | | |
| l13+ | Channel 13 - Non-inverting Input | | |
| l13- | Channel 13 - Ground | | |
| 114+ | Channel 14 - Non-inverting Input | | |
| l14- | Channel 14 - Ground | | |

The channels can be configured to receive input signal as TTL or dry contact input.

(6). Connector for RS-485 Screw Terminal

| RS-485 CONNECTOR | | | | | |
|------------------|-----------------------------|---------------------------------|-----|--|--|
| PIN NUMBER - + S | | | | | |
| ASSIGNMENT | Inverting Input / Output | Non-inverting Input / Output | GND | | |

Connector for RS-485 Screw Terminal supports MODBUS RTU to connect to other devices for users to read and download data to their personal computers or integrate them to other SCADA software.

(7). Connector for 4~20mA Analog Output

INPUT AND OUTPUT CONNECTIONS

| SCREW TERMINAL | ASSIGNMENT |
|----------------|---------------|
| l1+ | 4~20mA Output |
| l1- | Ground |
| 12+ | 4~20mA Output |
| 12- | Ground |

Any analog output interface can be configured as a link or replica of any analog input or remote data or screen control output.

(8). Connector for 10/100M, auto selection

The GM-100 includes full networking capabilities out of the box. The system supports MODBUS TCP and UDP protocols to communicate with other devices. Through MODBUS TCP or UDP protocol, users can access read-in data, which can be integrated with Supervisory Control And Data Acquisition (SCADA) system. A built-in web server enables users to read condition of I/O through web browsers such as IE, Chrome and Safari. The default IP address is 192.168.0.18. The Port number of MODBUS TCP is 502, UDP port number is 4800.

(9). Reset Button

Press the button to rest DAQ PCB.

(A). Operation Mode DIP Switch S1

| S1 SWITCH SETTING | | | OPERATION MODE SELECTION | |
|-------------------|-----|-----|-----------------------------|-------------------------------|
| 4 | 3 | 2 | 1 | |
| ON | ON | ON | ON | Calibration (in factory only) |
| ON | ON | ON | OFF | Calibration (in factory only) |
| ON | ON | OFF | OFF | Demo Mode |
| OFF | OFF | OFF | ON | Run Mode |
| OFF | OFF | OFF | OFF | Run Mode |

(B). Connector for Firmware Download

The connector is configured to update for firmware. It is the connector for engineers.

(C). Dip Switch for Signal Input Type Selection

| FUNCTION | VIRTUAL DRY CONTACT INPUT | 4~20mA (DEFAULT) |
|----------|---------------------------|---------------------|
| SWITCH 1 | ON | OFF |
| SWITCH 2 | ON | OFF |
| SWITCH 3 | ON | OFF |
| SWITCH 4 | ON | OFF |
| SWITCH 5 | ON | OFF |
| SWITCH 6 | ON | OFF |
| SWITCH 7 | ON | OFF |
| SWITCH 8 | ON | OFF |

(D). Buzzer

- (E). Buzzer Volume Adjustment Knob
- (F). External Output for Buzzer

Interface for external buzzer output

(G). Dip Switch for RS-485 Terminating Resistor

If the alarm is the last device on the RS-485 network, the dip switch of the last module of the alarm must be turned on.

APP. 2. DIMENSIONS AND WALL OPENING

UNIT : mm

APP. 3. INSTALLATION FOR METAL CASE AND FRONT PANEL

APP 4. CONNECTOR AND COUPLING TUBE WITH DISS

APP. 5. INSTALLATION FOR REMOTE TRANSDUCER

APP. 6. INSTALLATION FOR POWER SUPPLY AND GROUNDING

*Make sure the earth ground terminal is connected to case with washer nut.

APP. 7. WIRING OF TRANSDUCER TO SCREW TERMINAL

APP. 8. Modbus

APP. 8.1 The Query-Response Cycle

The master sends a query for a slave with a specific ID. All slaves check this query and send a response to the master only when slave has the same ID of query.

APP. 8.2 Modbus Function Code and Format

The function code of a Modbus message defines the action to be taken by the slave.

| Code | Modbus name | Description | |
|------|------------------------|---|------|
| 03 | Read Holding Registers | Read the content of read/write location | (4X |
| | | reference) | |
| 04 | Read Input Registers | Read the contents of read only location | (3X |
| | | reference) | |
| 16 | Pre-set Multiple | Set the contents of read/write location | (4X |
| | Registers | reference) | |

In RTU mode, messages start with a silent interval of at least 3.5 character times, and end with a similar interval of at least 3.5 character times. This is most easily implemented as a multiple of character times at the baud rate that is being used on the network.

All other fields are composed of 8-bit data. Query :

| Query . | | | | | | | |
|---------|-----------------------|-----------------|-----------------|-------------------|-------------------|---------------|---------------|
| Slave | Function | Start | Start | Number | Number | Error | Error |
| Address | Code 0x03, 0x04 | Address (Hi) | Address (Lo) | of Points (Hi) | of Points (Lo) | Check (Lo) | Check (Hi) |

| Res | ponse | : |
|-----|-------|---|

| Slave | Function | Byte | Data | Data | Error | Error |
|---------|----------|-------|------|------|-------|-------|
| Address | Code | Count | (Hi) | (Lo) | Check | Check |
| | 0x03, | | | | (Lo) | (Hi) |
| | 0x04 | | | | | |

Query :

| Response | : | |
|----------|----------|---|
| Slave | Function | S |

| Slave | Function | Start | Start | Number | Number | Error | Error |
|---------|----------|---------|---------|-----------|-----------|-------|-------|
| Address | Code | Address | Address | of Points | of Points | Check | Check |
| | 0x10 | (Hi) | (Lo) | (Hi) | (Lo) | (Lo) | (Hi) |

APP. 8.3 Communication Examples

Please refer to APP. 9. Registers Map for more details. Example 1: 03 Read Holding Registers Query:

| | Code (Hex) |
|----------------------|------------|
| Slave Address | 02 |
| Function | 03 |
| Starting Address Hi | 00 |
| Starting Address Lo | 20 |
| No. of Points Hi | 00 |
| No. of Points Lo | 01 |
| Error Check (CRC Lo) | 85 |
| Error Check (CRC Hi) | F3 |

Response:

| | Code (Hex) |
|----------------------|------------|
| Slave Address | 02 |
| Function | 03 |
| Number of Bytes | 02 |
| Data 1 Hi | 00 |
| Data 1 Lo | 03 |
| Error Check (CRC Lo) | BC |
| Error Check (CRC Hi) | 45 |

Error Response:

| | Code (Hex) |
|----------------------|------------|
| Slave Address | 02 |
| 80+Function code | 83 |
| Error Code | 03 |
| Error Check (CRC Lo) | XX |
| Error Check (CRC Hi) | XX |

Example 2: 04 (0x04) Read Input Registers Qu<u>ery:</u>

| | Code (Hex) |
|----------------------|------------|
| Slave Address | 02 |
| Function | 04 |
| Starting Address Hi | 10 |
| Starting Address Lo | 00 |
| No. of Points Hi | 00 |
| No. of Points Lo | 01 |
| Error Check (CRC Lo) | 35 |
| Error Check (CRC Hi) | 39 |

Response:

| | Code (Hex) |
|----------------------|------------|
| Slave Address | 02 |
| Function | 04 |
| Number of Bytes | 02 |
| Data 1 Hi | 00 |
| Data 1 Lo | 03 |
| Error Check (CRC Lo) | BD |
| Error Check (CRC Hi) | 31 |

Error Response:

| | Code (Hex) |
|----------------------|------------|
| Slave Address | 02 |
| 80+Function code | 84 |
| Error Code | 02 |
| Error Check (CRC Lo) | XX |
| Error Check (CRC Hi) | XX |

Example 3: 16 (0x10) Write Multiple registers

| | Code (Hex) |
|----------------------|------------|
| Slave Address | 02 |
| Function | 10 |
| Starting Address Hi | 00 |
| Starting Address Lo | 02 |
| No. of Points Hi | 00 |
| No. of Points Lo | 01 |
| Number of Bytes | 02 |
| Data 1 Hi | 00 |
| Data 1 Lo | 03 |
| Error Check (CRC Lo) | F5 |
| Error Check (CRC Hi) | C1 |

Response:

| | Code (Hex) |
|----------------------|------------|
| Slave Address | 02 |
| Function | 10 |
| Starting Address Hi | 00 |
| Starting Address Lo | 02 |
| No. of Points Hi | 00 |
| No. of Points Lo | 01 |
| Error Check (CRC Lo) | 00 |
| Error Check (CRC Hi) | 03 |

Error Response:

| | Code (Hex) |
|----------------------|------------|
| Slave Address | 02 |
| 80+Function code | 84 |
| Error Code | XX |
| Error Check (CRC Lo) | XX |
| Error Check (CRC Hi) | XX |

APP. 9. Registers Map

| Input Register Number | Data Type | Name of Parameter | Function description |
|-----------------------------|-----------|--------------------------------|--|
| 1 | UINT16 | AI_CH1_Channel InUse | Channel in use of analog input channel 1 (0: Disable 1: |
| 2 | INT32 | AI_CH1_PhysicalValue | Physical value of analog input channel 1: This value is multiplied by 1000. For example, the physical value is 12 345 when received data is 12345 |
| 4 | INT32 | AI_CH1_LLimit | Alarm of low limit value of analog input channel 1: This value is multiplied by 1000. For example, the low limit value is 12.345 when received data is 12345. |
| 6 | INT32 | AI_CH1_ULimit | Alarm of high limit value of analog input channel 1: This value is multiplied by 1000. For example, the high limit value is 12.345 when received data is 12345. |
| 8 | INT16 | AI_CH1_SuspendCountD ownMin | Remaining times of alarm suspend of analog input channel 1: In alarm state, alarm suspend is disable when remaining times is 0. The unit of this parameter is minute. |
| 9 | UINT16 | AI_CH1_Status | Status of analog input channel 1 bit 2 Sensor Error 0:Normal, 1:Error 3 Silence 0:Disable, 1:Enable 6 Low Alarm 0:No alarm, 1:Alarm 7 High Alarm 0:No alarm 1:Alarm |
| 10 | UINT16 | AI_CH2_Channel InUse | Channel in use of analog input channel 2 (0: Disable 1: Enable) |
| 11 | INT32 | AI_CH2_PhysicalValue | Physical value of analog input channel 2: This value is multiplied by 1000. For example, the physical value is 12 345 when received data is 12345 |
| 13 | INT32 | AI_CH2_LLimit | Alarm of low limit value of analog input channel 2: This value is multiplied by 1000. For example, the low limit value is 12.345 when received data is 12345. |
| 15 | INT32 | AI_CH2_ULimit | Alarm of high limit value of analog input channel 2: This value is multiplied by 1000. For example, the high limit value is 12.345 when received data is 12345. |
| 17 | INT16 | AI_CH2_SuspendCountD ownMin | Remaining times of alarm suspend of analog input channel 2: In alarm state, alarm suspend is disable when remaining times is 0. The unit of this parameter is minute |
| 18 | UINT16 | AI_CH2_Status | Status of analog input channel 2 bit 2 Sensor Error 0:Normal, 1:Error 3 Silence 0:Disable, 1:Enable 6 Low Alarm 0:No alarm, 1:Alarm 7 High Alarm 0:No alarm 1:Alarm |
| 19 | UINT16 | AI_CH3_Channel InUse | Channel in use of analog input channel 3 (0: Disable 1: Enable) |
| 20 | INT32 | AI_CH3_PhysicalValue | Physical value of analog input channel 3: This value is multiplied by 1000. For example, the physical value is 12.345 when received data is 12345. |
| 22 | INT32 | AI_CH3_LLimit | Alarm of low limit value of analog input channel 3: This value is multiplied by 1000. For example, the low limit value is 12.345 when received data is 12345. |
| 24 | INT32 | AI_CH3_ULimit | Alarm of high limit value of analog input channel 3: This value is multiplied by 1000. For example, the high limit value is 12.345 when received data is 12345. |
| 26 | INT16 | AI_CH3_SuspendCountD ownMin | Remaining times of alarm suspend of analog input channel 1: In alarm state, alarm suspend is disable when remaining times is 0. The unit of this parameter is minute. |
| 27 | UINT16 | AI_CH3_Status | Status of analog input channel 3 bit |

| | | | 2 Sensor Error 0:Normal, 1:Error |
|----|--------|--------------------------------|--|
| | | | 3 Silence 0:Disable, 1:Enable |
| | | | 7 High Alarm 0:No alarm, 1:Alarm |
| 28 | UINT16 | AI_CH4_Channel InUse | Channel in use of analog input channel 4 (0: Disable 1: Enable) |
| 29 | INT32 | AI_CH4_PhysicalValue | Physical value of analog input channel 4: This value is multiplied by 1000. For example, the physical value is 12.345 when received data is 12345. |
| 31 | INT32 | AI_CH4_LLimit | Alarm of low limit value of analog input channel 4: This value is multiplied by 1000. For example, the low limit value is 12.345 when received data is 12345. |
| 33 | INT32 | AI_CH4_ULimit | Alarm of high limit value of analog input channel 4: This value is multiplied by 1000. For example, the high limit value is 12.345 when received data is 12345. |
| 35 | INT16 | AI_CH4_SuspendCountD ownMin | Remaining times of alarm suspend of analog input channel 4: In alarm state, alarm suspend is disable when remaining times is 0. The unit of this parameter is minute. |
| 36 | UINT16 | AI_CH4_Status | Status of analog input channel 4 bit 2 Sensor Error 0:Normal, 1:Error 3 Silence 0:Disable, 1:Enable 6 Low Alarm 0:No alarm, 1:Alarm 7 High Alarm 0:No alarm, 1:Alarm |
| 37 | UINT16 | AI_CH5_Channel InUse | Channel in use of analog input channel 5 (0: Disable 1: Enable) |
| 38 | INT32 | AI_CH5_PhysicalValue | Physical value of analog input channel 5: This value is multiplied by 1000. For example, the physical value is 12.345 when received data is 12345. |
| 40 | INT32 | AI_CH5_LLimit | Alarm of low limit value of analog input channel 5: This value is multiplied by 1000. For example, the low limit value is 12.345 when received data is 12345. |
| 42 | INT32 | AI_CH5_ULimit | Alarm of high limit value of analog input channel 5: This value is multiplied by 1000. For example, the high limit value is 12.345 when received data is 12345. |
| 44 | INT16 | AI_CH5_SuspendCountD ownMin | Remaining times of alarm suspend of analog input channel 5: In alarm state, alarm suspend is disable when remaining times is 0. The unit of this parameter is minute. |
| 45 | UINT16 | AI_CH5_Status | Status of analog input channel 5 bit 2 Sensor Error 0:Normal, 1:Error 3 Silence 0:Disable, 1:Enable 6 Low Alarm 0:No alarm, 1:Alarm 7 High Alarm 0:No alarm 1:Alarm |
| 46 | UINT16 | AI_CH6_Channel InUse | Channel in use of analog input channel 6 (0: Disable 1: Enable) |
| 47 | INT32 | AI_CH6_PhysicalValue | Physical value of analog input channel 6: This value is multiplied by 1000. For example, the physical value is 12.345 when received data is 12345. |
| 49 | INT32 | AI_CH6_LLimit | Alarm of low limit value of analog input channel 6: This value is multiplied by 1000. For example, the low limit value is 12.345 when received data is 12345. |
| 51 | INT32 | AI_CH6_ULimit | Alarm of high limit value of analog input channel 6: This value is multiplied by 1000. For example, the high limit value is 12.345 when received data is 12345. |
| 53 | INT16 | AI_CH6_SuspendCountD ownMin | Remaining times of alarm suspend of analog input channel 6: In alarm state, alarm suspend is disable when remaining times is 0. The unit of this parameter is minute. |
| 54 | UINT16 | AI_CH6_Status | Status of analog input channel 6 bit 2 Sensor Error 0:Normal, 1:Error 3 Silence 0:Disable, 1:Enable 6 Low Alarm 0:No alarm, 1:Alarm 7 High Alarm 0:No alarm, 1:Alarm |
| 55 | UINT16 | AI_CH7_Channel InUse | Channel in use of analog input channel 7 (0: Disable 1: Enable) |
| 56 | INT32 | AI_CH7_PhysicalValue | Physical value of analog input channel 7: This value is multiplied by 1000. For example, the physical value is 12.345 when received data is 12345. |
| 58 | INT32 | AI_CH7_LLimit | Alarm of low limit value of analog input channel 7: This value is multiplied by 1000. For example, the low limit |

| | | | value is 12.345 when received data is 12345. |
|----|--------|---------------------------------|--|
| 60 | INT32 | AI_CH7_ULimit | Alarm of high limit value of analog input channel 7: This value is multiplied by 1000. For example, the high limit value is 12.345 when received data is 12345. |
| 62 | INT16 | AI_CH7_SuspendCountD ownMin | Remaining times of alarm suspend of analog input channel 7: In alarm state, alarm suspend is disable when remaining times is 0. The unit of this parameter is minute. |
| 63 | UINT16 | AI_CH7_Status | Status of analog input channel 7 bit 2 Sensor Error 0:Normal, 1:Error 3 Silence 0:Disable, 1:Enable 6 Low Alarm 0:No alarm, 1:Alarm 7 High Alarm 0:No alarm, 1:Alarm |
| 64 | UINT16 | AI_CH8_Channel InUse | Channel in use of analog input channel 8 (0: Disable 1: Enable) |
| 65 | INT32 | AI_CH8_PhysicalValue | Physical value of analog input channel 8: This value is multiplied by 1000. For example, the physical value is 12.345 when received data is 12345. |
| 67 | INT32 | AI_CH8_LLimit | Alarm of low limit value of analog input channel 8: This value is multiplied by 1000. For example, the low limit value is 12.345 when received data is 12345. |
| 69 | INT32 | AI_CH8_ULimit | Alarm of high limit value of analog input channel 8: This value is multiplied by 1000. For example, the high limit value is 12.345 when received data is 12345. |
| 71 | INT16 | AI_CH8_SuspendCountD ownMin | Remaining times of alarm suspend of analog input channel 8: In alarm state, alarm suspend is disable when remaining times is 0. The unit of this parameter is minute. |
| 72 | UINT16 | AI_CH8_Status | Status of analog input channel 8 bit 2 Sensor Error 0:Normal, 1:Error 3 Silence 0:Disable, 1:Enable 6 Low Alarm 0:No alarm, 1:Alarm 7 High Alarm 0:No alarm, 1:Alarm |
| 73 | UINT16 | DI_Data | Status (0 or 1) of digital input: Bit6: Digital input channel 7 7: Digital input channel 8 8: Digital input channel 8 8: Digital input channel 9 9: Digital input channel 9 9: Digital input channel 10 10: Digital input channel 6 115: Digital input channel 6 1211: Digital input channel 6 11: Digital input channel 6 |
| 74 | UINT16 | DI_Alarm | Alarm status of digital input: Bit 0 0: DI CH1 no alarm, 1: DI CH1 alarm 1 0: DI CH2 no alarm, 1: DI CH2 alarm |
| 75 | INT16 | DI_CH1_SuspendCountD ownMin | Remaining times of alarm suspend of digital input channel 1: In alarm state, alarm suspend is disable when remaining times is 0. The unit of this parameter is minute. |
| 76 | INT16 | DI_CH2_SuspendCountD ownMin | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 77 | INT16 | DI_CH3_SuspendCountD ownMin | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 78 | INT16 | DI_CH4_SuspendCountD ownMin | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 79 | INT16 | DI_CH5_SuspendCountD ownMin | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 80 | INT16 | DI_CH6_SuspendCountD | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 81 | INT16 | DI_CH7_SuspendCountD | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 82 | INT16 | DI_CH8_SuspendCountD ownMin | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 83 | INT16 | DI_CH9_SuspendCountD ownMin | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 84 | INT16 | DI_CH10_SuspendCount DownMin | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 85 | INT16 | DI_CH11_SuspendCount | (Please refer to the function description of |

| | | DownMin | DI_CH1_SuspendCountDownMin) |
|-----|--------|---------------------------------|--|
| 86 | INT16 | DI_CH12_SuspendCount DownMin | (Please refer to the function description of DI_CH1_SuspendCountDownMin) |
| 87 | INT16 | DI_CH13_SuspendCount DownMin | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 88 | INT16 | DI_CH14_SuspendCount DownMin | (Please refer to the function description of DI CH1 SuspendCountDownMin) |
| 89 | UINT16 | DO_Status | Status of digital output ∘ |
| | | | 0Relay1 0:open 1:short |
| | | | 2Relay2 0:open 1:short |
| | | | 3Relay4 0:open 1:short |
| | | | 5Relay6 0:open 1:short |
| 90 | UINT16 | DA CH1 µA | 6Relay7 0:open 1:short Analog output channel 1: The unit of parameter is // A |
| 92 | UINT16 | DA CH2 uA | Analog output channel 2: The unit of parameter is μA |
| 94 | INT32 | AI_CH1_Hysteresis | Hysteresis of analog input channel 1: This value is multiplied by 1000. For example, the hysteresis value is 5 when received data is 5000. |
| 96 | INT16 | AI_CH1_SilenceTime | Silence time of analog input channel 1: The unit of this parameter is minute. Buzzer is not active when value is set to -1 |
| 97 | INT32 | AI_CH1_mV | Voltage of analog input channel 1: The unit of this parameter is mV. |
| 99 | INT32 | AI_CH2_Hysteresis | Hysteresis of analog input channel 2: This value is multiplied by 1000. For example, the hysteresis value is 5 when received data is 5000. |
| 101 | INT16 | AI_CH2_SilenceTime | Silence time of analog input channel 2: The unit of this parameter is minute. Buzzer is not active when value is set to -1. |
| 102 | INT32 | AI_CH2_mV | Voltage of analog input channel 2: The unit of this parameter is mV. |
| 104 | INT32 | AI_CH3_Hysteresis | Hysteresis of analog input channel 3: This value is multiplied by 1000. For example, the hysteresis value is 5 when received data is 5000. |
| 106 | INT16 | AI_CH3_SilenceTime | Silence time of analog input channel 3: The unit of this parameter is minute. Buzzer is not active when value is set to -1. |
| 107 | INT32 | AI_CH3_mV | Voltage of analog input channel 3: The unit of this parameter is mV. |
| 109 | INT32 | AI_CH4_Hysteresis | Hysteresis of analog input channel 4: This value is multiplied by 1000. For example, the hysteresis value is 5 when received data is 5000. |
| 111 | INT16 | AI_CH4_SilenceTime | Silence time of analog input channel 4: The unit of this parameter is minute. Buzzer is not active when value is set to -1. |
| 112 | INT32 | AI_CH4_mV | Voltage of analog input channel 4: The unit of this parameter is mV. |
| 114 | INT32 | AI_CH5_Hysteresis | Hysteresis of analog input channel 5: This value is multiplied by 1000. For example, the hysteresis value is 5 when received data is 5000. |
| 116 | INT16 | AI_CH5_SilenceTime | Silence time of analog input channel 5: The unit of this parameter is minute. Buzzer is not active when value is set to -1. |
| 117 | INT32 | AI_CH5_mV | Voltage of analog input channel 5: The unit of this parameter is mV. |
| 119 | INT32 | AI_CH6_Hysteresis | Hysteresis of analog input channel 6: This value is multiplied by 1000. For example, the hysteresis value is 5 when received data is 5000. |
| 121 | INT16 | AI_CH6_SilenceTime | Silence time of analog input channel 6: The unit of this parameter is minute. Buzzer is not active when value is set to -1. |
| 122 | INT32 | AI_CH6_mV | Voltage of analog input channel 6: The unit of this parameter is mV. |
| 124 | INT32 | AI_CH7_Hysteresis | Hysteresis of analog input channel 7: This value is multiplied by 1000. For example, the hysteresis value is 5 when received data is 5000. |
| 126 | INT16 | AI_CH7_SilenceTime | Silence time of analog input channel 7: The unit of this parameter is minute. Buzzer is not active when value is set to -1. |
| 127 | INT32 | AI_CH7_mV | Voltage of analog input channel 7: The unit of this |

| | | | parameter is mV. |
|-----|---------|----------------------|---|
| 129 | INT32 | AI_CH8_Hysteresis | Hysteresis of analog input channel 8: This value is |
| | | | multiplied by 1000. For example, the hysteresis value is |
| 131 | INT16 | AL CH8 SilenceTime | Silence time of analog input channel 8: The unit of this |
| 131 | | AI_CI16_SilenceTime | parameter is minute. Buzzer is not active when value is |
| | | | set to -1. |
| 132 | INT32 | AI_CH8_mV | Voltage of analog input channel 8: The unit of this |
| | | | parameter is mV. |
| 134 | INT16 | DI_CH1_SilenceTime | Silence time of digital input channel 1. The unit of this |
| | | | parameter is minute. Buzzer is not active when value is |
| 135 | INT16 | DL CH2 SilenceTime | (Please refer to the function description of |
| | | | DI CH1 SilenceTime) |
| 136 | INT16 | DI_CH3_SilenceTime | (Please refer to the function description of |
| | | | DI_CH1_SilenceTime) |
| 137 | INT16 | DI_CH4_SilenceTime | (Please refer to the function description of |
| 120 | INIT16 | DI CHE SilongoTimo | DI_CH1_SlienceTime) |
| 130 | | DI_CH5_Slience fille | DI CH1 SilenceTime) |
| 139 | INT16 | DI CH6 SilenceTime | (Please refer to the function description of |
| | | | DI_CH1_SilenceTime) |
| 140 | INT16 | DI_CH7_SilenceTime | (Please refer to the function description of |
| | 111740 | | DI_CH1_SilenceTime) |
| 141 | IN I 16 | DI_CH8_SilenceTime | (Please refer to the function description of |
| 1/2 | INT16 | DI CHQ SilenceTime | (Please refer to the function description of |
| 142 | | DI_CH9_Silence Time | DI CH1 SilenceTime) |
| 143 | INT16 | DI CH10 SilenceTime | (Please refer to the function description of |
| | | | DI_CH1_SilenceTime) |
| 144 | INT16 | DI_CH11_SilenceTime | (Please refer to the function description of |
| | | | DI_CH1_SilenceTime) |
| 145 | INT16 | DI_CH12_SilenceTime | (Please refer to the function description of |
| 146 | INT16 | DI CH13 SiloncoTimo | (Please refer to the function description of |
| 140 | | | DI CH1 SilenceTime) |
| 147 | INT16 | DI CH14 SilenceTime | (Please refer to the function description of |
| | | | DI_CH1_SilenceTime) |
| | | | |